

Total No. of Questions : 8]

SEAT No. :

P2366

[4937]-4001

[Total No. of Pages : 3

M.Sc.

COMPUTER SCIENCE

**CS - 402 : Parallel Computing
(2013 Pattern) (Semester - IV)**

Time : 3 Hours]

[Max. Marks : 50

Instructions to the candidates:

- 1) *Attempt any five questions out of eight.*
- 2) *All questions carry equal marks.*
- 3) *Figures to the right indicate full marks.*
- 4) *Neat diagrams must be drawn wherever necessary.*

Q1) a) Explain Amdahl's law in parallel processing. **[2]**

b) Explain in brief data parallel model (partitioned global address space model). **[4]**

c) Explain what is meant by deadlock, and blocking & non- blocking communications. **[4]**

Q2) a) Define speedup and efficiency of a parallel program. **[2]**

b) What is scalability of parallel program? What is super - linear speedup?**[4]**

c) Explain UMA and NUMA computer architectures. Draw block diagram of each architecture. **[4]**

Q3) a) Draw a schematic of a mesh-connected parallel computer. **[2]**

b) Define total network bandwidth and bisection bandwidth of an interconnection network. **[4]**

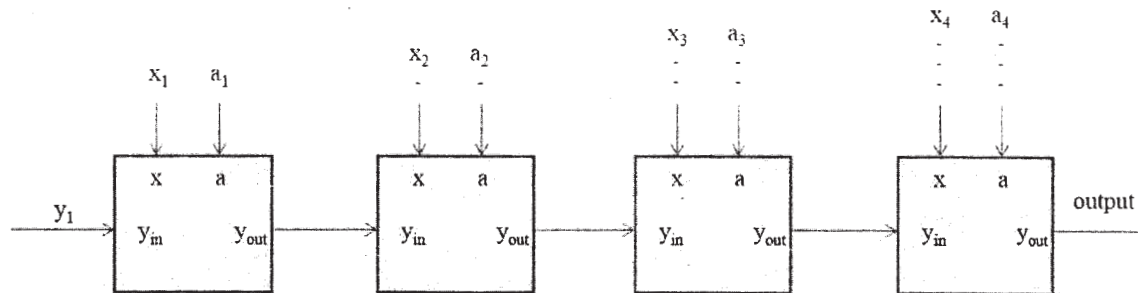
What are the values of these parameters for a ring of n computing elements (processors with own memory)? Assume B to be the bandwidth of an individual link.

c) Explain in brief MPI_Comm_size, MPI_Comm_rank and MPI_COMM_WORLD. **[4]**

P.T.O.

Q4) a) Explain in brief MPI_Init and MPI_Finalize. [2]

b) The pipeline given below consists of four stages and it is synchronous, i.e., each cell finishes its operation in one clock cycle and the (input/output) data advances one step forward [3]



If each stage performs the operation

$$y_{out} = y_{in} + a.x$$

What will be the final output after four clock cycles?

c) Describe packet switching, virtual cut through routing, and wormhole routing in direct interconnection networks. [5]

Q5) a) Explain single and master directives in OpenMP. [2]

b) Does the following code snippet lead to a deadlock? Is so, give at least two methods that you can use to avoid this deadlock. [3]

```
if (myrank == 0){
    MPI_Send (in, 10, MPI_INT, 1, 1, MPI_COMM_WORLD);
    MPI_Send (out, 10, MPI_INT, 1, 2, MPI_COMM_WORLD);
}
else if (myrank == 1){
    MPI_Recv (out, 10, MPI_INT, 0, 2, MPI_COMM_WORLD);
    MPI_Recv (in, 10, MPI_INT, 0, 1, MPI_COMM_WORLD);
}
```

Note: The parameters in the above functions represent: buffer, count of data type to be sent/received, data-type, destination/source process-id, message-tag, and communicator, respectively.

- c) What is shared memory parallel programming paradigm? Describe with schematic the OpenMP shared parallel programming model. [5]
- Q6)** a) Distinguish between MPI_Bcast and MPI_Send. [2]
b) What is a thread? Why are the advantages of using threads? Describe different methods in Open MP to create threads. [4]
c) What is a critical section in parallel program? Which OpenMP directive can be used to implement a critical section? [4]
- Q7)** a) Explain any two scheduling strategies of a for directive in OpenMP. [5]
b) Explain task parallelism using spawn and sync keywords in Cilk++ with an example. [5]
- Q8)** a) Explain the concepts of grids, thread blocks, threads, and warps in CUDA programming. [5]
b) What is the purpose of GPU and how does it differ from CPU? [5]

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