

UNIVERSITY OF PUNE

[4363]-185

T. E. (E & TC) Examination May 2013

Digital Signal Processing

(2008 Course) (Sem-I)

Total No. of Questions : 12
[Time : 3 Hours]

[Total No. of Printed Pages : 4]
[Max. Marks : 100]

Instructions :

- (1) Answer 3 question from section-I and 3 question from section-II
- (2) Answers to the **two sections** should be written in **separate -books**.
- (3) Neat diagram must be drawn wherever necessary.
- (4) Black figures to the right indicate full marks.
- (5) Your answers will be valued as whole.
- (6) Use of logarithmic tables, slide rule, Mollier charts, electronic pocket calculator and steam tables is allowed.
- (7) Assume suitable data, if necessary.

SECTION-I

Q1.

a) Find the convolution of following sequences

1) $x(n) = 2^n$ and $h(n) = (1/2)^n u(n)$

2) $x(n) = n + 2$ for $0 \leq n \leq 3$ and $h(n) = a^n u(n)$ [8]

b) Define stability. Explain the condition for system to be stable in terms of impulse Response. Test the stability of the system whose impulse response is

$h(n) = (1/2)^n u(n)$

$h(n) = (3)^{-n} u(n)$ [10]

OR

Q2.

a) Determine the direct form-I and II realization for the following system.

Show all Steps properly. [10]

$$y(n) = -0.1y(n-1) + 0.2y(n-2) + 3x(n) + 3.6x(n-1) + 0.6x(n-2)$$

$$y(n) = 0.251y(n-1) + 0.05y(n-2) + x(n) - 2x(n-2)$$

- b) Explain the basic elements of DSP system. Explain the advantages of DSP over analog system [8]

Q3.

- a) Find out the relation between DTFS and DFT. Find n=4 point DFT for $x(n) = \{1,0,1,0\}$ [8]
- b) Find the circular convolution for following sequences using graphical method [8]
- 1) $x_1(n) = \delta(n) + \delta(n-1) + \delta(n-2)$
 $x_2(n) = 2\delta(n) - \delta(n-1) + 2\delta(n-2)$
 - 2) $x_1(n) = \delta(n) + \delta(n-1) - \delta(n-2) - \delta(n-3)$
 $x_2(n) = \delta(n) - \delta(n-2) + \delta(n-4)$

OR

Q4.

- a) Explain and prove the following properties of DFT [8]
- 1) Periodicity
 - 2) Complex conjugate property of DFT
 - 3) Time reversal
 - 4) Circular time shifting
- b) Find the DFT of a sequence $x(n) = \{1,2,3,4,4,3,2,1\}$ using DIT algorithm. Draw 8-point DIT FFT flow graph and show all values properly. [8]

Q5.

- a) Define ROC. Find the Z transform and sketch the corresponding ROC for following signals [8]
- 1) $x(n) = \{1,2,3,4,5,9\}$ (origin is at 3)
 - 2) $x(n) = (n + 0.5) \left(\frac{1}{3}\right)^n u(n)$
- b) Find the $H(z)$ and poles of the system
 $y(n) - 0.25y(n-1) + 0.25y(n-2) - 0.0625y(n-3) = 2x(n) + 3x(n-1)$
 And state the system is stable or not. [8]

OR

Q6.

- a) State the convolution property of Z-transform and hence find causal sequence $x(n)$ for [8]

$$X(z) = \frac{[6+z^{-1}]}{[(1+0.25z^{-1})(1+0.5z^{-1})]}$$

- b) Determine the inverse Z transform of the function [8]

1) $X(z) = \frac{[8z-19]}{[(z-2)(z-3)]}$ $x(n)$ is causal sequence

2) $\frac{[z^3+z^2]}{[(z-1)(z-3)]}$ ROC: $|z| > 3$

SECTION-II

Q7.

- a) Differentiate between FIR and IIR filters. In case of IIR filter, compare impulse invariant method and Bilinear Transformation method. [8]

- b) Design a complete digital low pass Butterworth filter for $T=1$ for following specifications using an impulse invariant method [10]

$$0.8 \leq |H(e^{jw})| \leq 1 \quad \text{for} \quad 0 \leq w \leq 0.2\pi$$

$$|h(e^{jw})| \leq 0.2 \quad \text{for} \quad 0.6\pi \leq w \leq \pi$$

Q8.

- a) Design the seven coefficient FIR low-pass filter using frequency sampling method with following specifications. Plot the magnitude response of the resulting filter [10]

$$H(e^{jw}) = e^{-j(N-1)w/2} \quad \text{for} \quad 0 \leq |w| \leq \frac{\pi}{2}$$

$$H(e^{jw}) = 0 \quad \text{for} \quad \frac{\pi}{2} \leq |w| \leq \pi$$

- b) What is the nature of phase response of FIR filter? Derive the condition of linear phase of FIR filter. [8]

Q9.

- a) Draw the block schematic for decimator and explain the need for a filter. Derive the expression for decimated output signal i.e. $y(m)$ and draw the spectrum of the signal after filtering and after decimation process. [10]

- b) Explain the need for multistage design. How will you select decimation factors for different stages for multistage implementation. [6]

OR

Q10.

- a) Why should we use an interpolator first before a decimator in case of sampling rate converter by a factor of I/D. Derive the equation for the output of the sampling rate converter I/D [10]
- b) Explain how Multi-rate sampling can be used in acquisition of high Quality data? [6]

Q11.

- a) Explain the need of DSP processor and features required in DSP processor [6]
- b) Explain pipelining concept. Also explain MAC, ALU and Barrel Shifter unit of DSP processor. [10]

OR

Q12.

- a) Differentiate between DSP processor with conventional microprocessor architectures? Explain the architecture of TMS320C67XX listing its important features [10]
- b) Explain the application of DSP processor in speech processing [6]