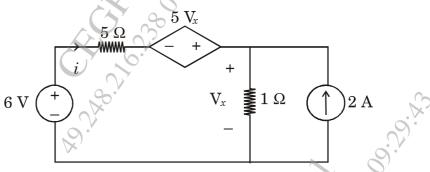
Total No. of Questions—8] [Total No. of Printed Pages—3	
Seat No.	[5252]-533
S.E. (E & TC and Electronics) (I Semester) EXAMINATION, 2017	
ELECTRICAL CIRCUITS AND MACHINES	
(2015 PATTERN)	
Time : 7	Swo HoursMaximum Marks : 50
<i>N.B.</i> :	(i) Answer Q.1 or Q.2, Q.3 or Q.4, Q.5 or Q.6, Q.7 or Q.8.
	( <i>ii</i> ) Figures to the right indicate full marks.
	(iii) Neat diagrams must be drawn wherever necessary.
	(iv) Use of non-programmable electronic pocket culculator is allowed.
	(v) Assume suitable data if necessary.
<b>1.</b> ( <i>a</i> )	Using superposition theorem, calculate current 'i' for the circuit
	shown in the following fig. [6]



(b) Derive the e.m.f. equation of a single phase transformer. [6] Or

2. (a) The equivalent circuit of 20 kVA, 2500 V/250 V, 50 Hz. single phase transformer gave the following test results : [6] O.C. Test (L.V. Side) : 250 V, 1.4 A, 105 W S.C. Test (H.V. Side) : 104 V, 8 A, 320 W Calculate the parameters of approximate equivalent circuit.

P.T.O.

- (b) State and explain Thevenin's theorem and Norton's theorem.[6]
- 3. (a) A 200V, 4 pole, lap wound, d.c. shunt motor has 800 conductors on its armature. The resistance of the armature winding is 0.5 Ω and that of shunt field winding is 200 Ω. The motor takes a current of 21 A, the flux per pole is 30 mWb. Find the speed and the gross torque developed in the motor. [6]
  (b) Obtain the armatic for a series of the speed and the gross torque developed in the motor. [6]
  - (b) Obtain the condition for maximum torque for 3 phase induction motor. State the equation for maximum torque. [6]
     Or
- (a) The power input to the rotor of a 400 V, 50 Hz, 6 pole, three-phase induction motor is 75 kW. Motor has 2 kW stator losses and mechanical losses 750 watts. If frequency of e.m.f. induced in the rotor circuit has 4 Hz, determine :
  - (*i*) Slip of the motor
  - (ii) Rotor speed
  - (iii) Rotor copper loss per phase
  - (iv) Output of the motor
  - (v) Input of the motor
  - (vi) Efficiency of motor.
  - (b) Draw and explain the characteristics of d.c. series motor.[6]

[6]

- **5.** (*a*) What are universal motors ? Explain torque-speed characteristic of compensated type and non-compensated type universal motor.[7]
  - (b) Distinguish between brushless DC motor and Conventional DC motor. [6]

Or

- 6. (a) Explain construction, principle and applications of Reluctance motor. [7]
  - (b) What are brushless motors and explain with neat diagram operation of unipolar brushless DC motor. [6]

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- 7. (a) Compare Variable Reluctance and Permanent Magnet stepper motors. [7]
  - (b) Explain the working and features of armature controlled d.c. servomotor. [6]

Or

- 8. (a) Explain the principle of operation of shaded pole induction motor along with the torque-slip characteristics and state its applications. [7]
  - (b) What are stepper motors ? Explain any one type in detail.[6]

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