

[4263] - 344

T.E. (Computer Engineering)
DIGITAL SIGNAL PROCESSING
(2008 Pattern) (Sem. - I)

Time : 3 Hours]

[Max. Marks : 100

Instructions to the candidates:

- 1) *Answer any three questions from each section.*
- 2) *Answers to the two sections should be written in separate answer books.*
- 3) *Figures to the right indicate full marks.*
- 4) *Assume suitable data, if necessary.*

SECTION - I



- Q1)** a) Define linear convolution. Explain different steps to calculate linear convolution with example. [6]
b) Define the impulse response of the DT system. Show that $h(n) = 0$ for $n < 0$, for a causal system. [6]
c) Explain quantization process in ADC. [4]

OR

- Q2)** a) Test the system $y(n) = x(n) + n x(n + 1)$ for causality, linearity and time invariance. [6]
b) State and explain the sampling theorem. [6]
c) Define the terms: natural & forced response for a causal system. [4]

- Q3)** a) Explain how N-point DFT and IDFT can be obtained by means of linear transformation matrix. [8]
b) State and prove differentiation property of F.T. [6]
c) Find $x((n + 2))_5$ and $x((-n))_5$ for the sequence $x(n) = \{1, 2, 3, 4\}$ [4]

OR

P.T.O.

- Q4)** a) Find the fourier transform of $x(n) = -a^n u(-n-1)$, where a is real. [6]
 b) What is the significance of N in DFT? Why it is necessary to have $N \geq L$ where L is length of DT signal. [6]
 c) Determine 2-point and 4-point DFT of a sequence $x(n) = u(n) - u(n-2)$. Compare the result. [6]

- Q5)** a) Draw a signal flow diagram for 8-point DFT using Decimation in Frequency (DIF) FFT algorithm. Obtain its computational complexity. [8]
 b) Why z-transform need to be specified only with ROC? What are the all possible ROCs for finite and infinite duration sequences? [8]

OR

- Q6)** a) Using residue method, obtain inverse Z transform from

$$X(z) = \frac{1}{(z-1)(z-3)} \quad [6]$$

- b) State and prove time reversal property of Z-transform. [6]
 c) Write a short note on bit reversal in FFT [4]

SECTION - II

- Q7)** a) With example, explain the method of simple geometric construction to obtain the phase and frequency of DT system. [10]
 b) An LTI system is represented by difference equation $y(n) = 0.7 y(n-1) - 0.1 y(n-2) + 2x(n) - x(n-2)$. [6]
 i) Find System function
 ii) Draw pole zero plot and check stability

OR

- Q8)** a) Find the frequency response of a system described by difference equation $y(n) - \frac{1}{2} y(n-1) = x(n) - \frac{1}{4} x(n-1)$. Plot magnitude of a frequency response. [10]
 b) Define a unilateral z-transform. What are the different characteristics of it? State time delay and time advanced property of unilateral z transform. [6]

Q9) a) Explain the design steps of IIR filter by using impulse invariance method and then find out $H(z)$ from $H(s) = \frac{2}{(s+1)(s+2)}$ with $F_s = 5$ Hz. [10]

b) State the characteristics of ideal filter. What are the advantages and disadvantages of digital filter over analog filter? [8]

OR

Q10) a) What are the two different methods to design FIR filter? Explain the design steps of each method. [8]

b) Compare: FIR and IIR filter. [6]

c) Write a short note on: Effect of finite word length. [4]

Q11) a) Draw and explain functional Block diagram of barrel shifter. [8]

b) Obtain parallel form realization for IIR filter having:

$$H(z) = \frac{3(2z^2 + 5z^2 + 8)}{(2z+1)(z+2)} \quad [8]$$

OR

Q12) a) Explain the application of DSP in speech processing. [8]

b) Draw and explain in brief the cascade form of FIR filter structure. [8]

